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1 Fast parallel image processing for robot vision for the purpose of extracting information about objects*Bolle, R.; Cernuschi, B.; Cooper, D.;*

Acoustics, Speech, and Signal Processing, IEEE International Conference on ICASSP '83.

, Volume: 8 , Apr 1983

Pages:126 - 127

IEEE CNF**2 A laser and a camera for mobile robot navigation***Wijesoma, W.S.; Kodagoda, K.R.S.; Balasuriya, A.P.;*

Control, Automation, Robotics and Vision, 2002. ICARCV 2002. 7th International

Conference on , Volume: 2 , 2-5 Dec. 2002

Pages:740 - 745 vol.2

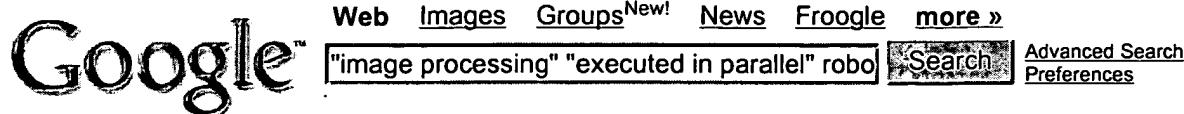
IEEE CNF**3 Road curb and intersection detection using a 2D LMS***Kodagoda, K.R.S.; Wijesoma, W.S.; Balasuriya, A.P.;*

Intelligent Robots and System, 2002. IEEE/RSJ International Conference on , Volume:

1 , 30 Sept.-5 Oct. 2002

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